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## CS 361, Lecture 17

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Outline $\qquad$

- Binary Search Trees
- Red-Black Trees
- Class Evaluation

Hash Tables implement the Dictionary ADT, namely:

- Insert $(\mathrm{x})-O(1)$ expected time, $\Theta(n)$ worst case
- Lookup (x) - $O(1)$ expected time, $\Theta(n)$ worst case
- Delete $(\mathrm{x})-O(1)$ expected time, $\Theta(n)$ worst case
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$\square$ Red-Black Trees $\qquad$

Red-Black trees (a kind of binary tree) also implement the Dictionary ADT, namely:

- Insert $(\mathrm{x})-O(\log n)$ time
- Lookup $(\mathrm{x})-O(\log n)$ time
- Delete $(\mathrm{x})-O(\log n)$ time
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$\qquad$
- Q: When would you use a Search Tree?
- A1: When need a hard guarantee on the worst case run times (e.g. "mission critical" code)
- A2: When want something more dynamic than a hash table (e.g. don't want to have to enlarge a hash table when the load factor gets too large)
- A3: Search trees can implement some other important operations...
- It's a binary tree
- Each node holds a key and record field, and a pointer to left and right children
- Binary Search Tree Property is maintained
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- Insert
- Lookup
- Delete
- Minimum/Maximum
- Predecessor/Successor
$\qquad$
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```
Inorder-TW(x){
    if (x is not nil){
        Inorder-TW(left(x));
        print key(x);
        Inorder-TW(right(x));
}
```

$\qquad$ Example Tree-Walk $\qquad$

- BSTs are arranged in such a way that we can print out the elements in sorted order in $\Theta(n)$ time
- Inorder Tree-Walk does this
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- Correctness?
- Run time?
- Let $h$ be the height of the tree
- The run time is $O(h)$
- Correctness???
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Search in BT $\qquad$
$\Gamma$

```
Tree-Search(x,k){
    if (x=nil) or (k = key(x)){
        return x;
    }
    if (k<key(x)){
        return Tree-Search(left(x),k);
    }else{
        return Tree-Search(right(x),k);
    }
}
```

In-Class Exercise $\qquad$

- Q1: What is the loop invariant for Tree-Search?
- Q2: What is Initialization?
- Q3: Maintenance?
- Q4: Termination?
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- Tree Minimum(x): Return the leftmost child in the tree rooted at $\times$
- Tree Maximum $(x)$ : Return the rightmost child in the tree rooted at $x$
- Case 1: If right subtree of $x$ is non-empty, $\operatorname{successor}(\mathrm{x})$ is just the leftmost node in the right subtree
- Case 2: If the right subtree of $x$ is empty and $x$ has a successor, then successor ( X ) is the lowest ancestor of $x$ whose left child is also an ancestor of $x$.

Tree-Successor $\qquad$ Insertion $\qquad$

```
Tree-Successor(x){
    if (right(x) != null){
        return Tree-Minimum(right(x));
    }
    y = parent(x);
    while (y!=null and x!=left(y)){
        x = y;
        y = parent(y);
    }
    return y;
}
```

Insert( $\mathrm{T}, \mathrm{x}$ )

1. Let $r$ be the root of $T$.
2. Do Tree-Search $(r, \operatorname{key}(x))$ and let $p$ be the last node processed in that search
3. If $p$ is nil (there is no tree), make $x$ the root of a new tree
4. Else if $\operatorname{key}(\mathrm{x}) \leq \mathrm{p}$, make $x$ the left child of $p$, else make $x$ the right child of $p$
$\qquad$
$\qquad$

- Code is in book, basically there are three cases, two are easy and one is tricky
- Case 1: The node to delete has no children. Then we just delete the node
- Case 2: The node to delete has one child. Then we delete the node and "splice" together the two resulting trees
- All of these operations take $O(h)$ time where $h$ is the height of the tree
- If $n$ is the number of nodes in the tree, in the worst case, $h$ is $O(n)$
- However, if we can keep the tree balanced, we can ensure that $h=O(\log n)$
- Red-Black trees can maintain a balanced BST

Case 3 $\qquad$

Case 3: The node, $x$ to be deleted has two children

1. Swap $x$ with Successor ( X ) (Successor $(\mathrm{x})$ has no more than 1 child (why?))
2. Remove $x$, using the procedure for case 1 or case 2.

Randomly Built BST $\qquad$

- What if we build a binary search tree by inserting a bunch of elements at random?
- Q: What will be the average depth of a node in such a randomly built tree? We'll show that it's $O(\log n)$
- For a tree $T$ and node $x$, let $d(x, T)$ be the depth of node $x$ in $T$
- Define the total path length, $P(T)$, to be the sum over all nodes $x$ in $T$ of $d(x, T)$
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$\qquad$
"Shut up brain or I'll poke you with a Q-Tip" - Homer Simpson
- Note that the average depth of a node in $T$ is

$$
\frac{1}{n} \sum_{x \in T} d(x, T)=\frac{1}{n} P(T)
$$

- Thus we want to show that $P(T)=O(n \log n)$
- Let $P(n)$ be the expected total depth of all nodes in a randomly built binary tree with $n$ nodes
- Note that for all $i, 0 \leq i \leq n-1$, the probability that $T_{l}$ has $i$ nodes and $T_{r}$ has $n-i-1$ nodes is $1 / n$.
- Thus $P(n)=\frac{1}{n} \sum_{i=0}^{n-1}(P(i)+P(n-i-1)+n-1)$

Analysis $\qquad$

- Let $T_{l}, T_{r}$ be the left and right subtrees of $T$ respectively.

Let $n$ be the number of nodes in $T$

- Then $P(T)=P\left(T_{l}\right)+P\left(T_{r}\right)+n-1$. Why?


## Analysis

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$$
\begin{align*}
P(n) & =\frac{1}{n} \sum_{i=0}^{n-1}(P(i)+P(n-i-1)+n-1)  \tag{1}\\
& =\frac{1}{n}\left(\sum_{i=0}^{n-1}(P(i)+P(n-i-1))+\frac{1}{n}\left(\sum_{i=0}^{n-1} n-1\right)\right)  \tag{2}\\
& =\frac{1}{n}\left(\sum_{i=0}^{n-1}(P(i)+P(n-i-1))+\Theta(n)\right.  \tag{3}\\
& =\frac{2}{n}\left(\sum_{k=1}^{n-1} P(k)\right)+\Theta(n) \tag{4}
\end{align*}
$$

$\qquad$

- We have $P(n)=\frac{2}{n}\left(\sum_{k=1}^{n-1} P(k)\right)+\Theta(n)$
- This is the same recurrence for randomized Quicksort
- In your hw (problem 7-2), you showed that the solution to this recurrence is $P(n)=O(n \log n)$
- The expected average depth of a node in a randomly built binary tree is $O(\log n)$
- This implies that operations like search, insert, delete take expected time $O(\log n)$ for a randomly built binary tree
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$P(n)$ is the expected total depth of all nodes in a randomly built binary tree with $n$ nodes.
- We've shown that $P(n)=O(n \log n)$
- There are $n$ nodes total
- Thus the expected average depth of a node is $O(\log n)$

Warning!

- In many cases, data is not inserted randomly into a binary search tree
- I.e. many binary search trees are not "randomly built"
- For example, data might be inserted into the binary search tree in almost sorted order
- Then the BST would not be randomly built, and so the expected average depth of the nodes would not be $O(\log n)$

