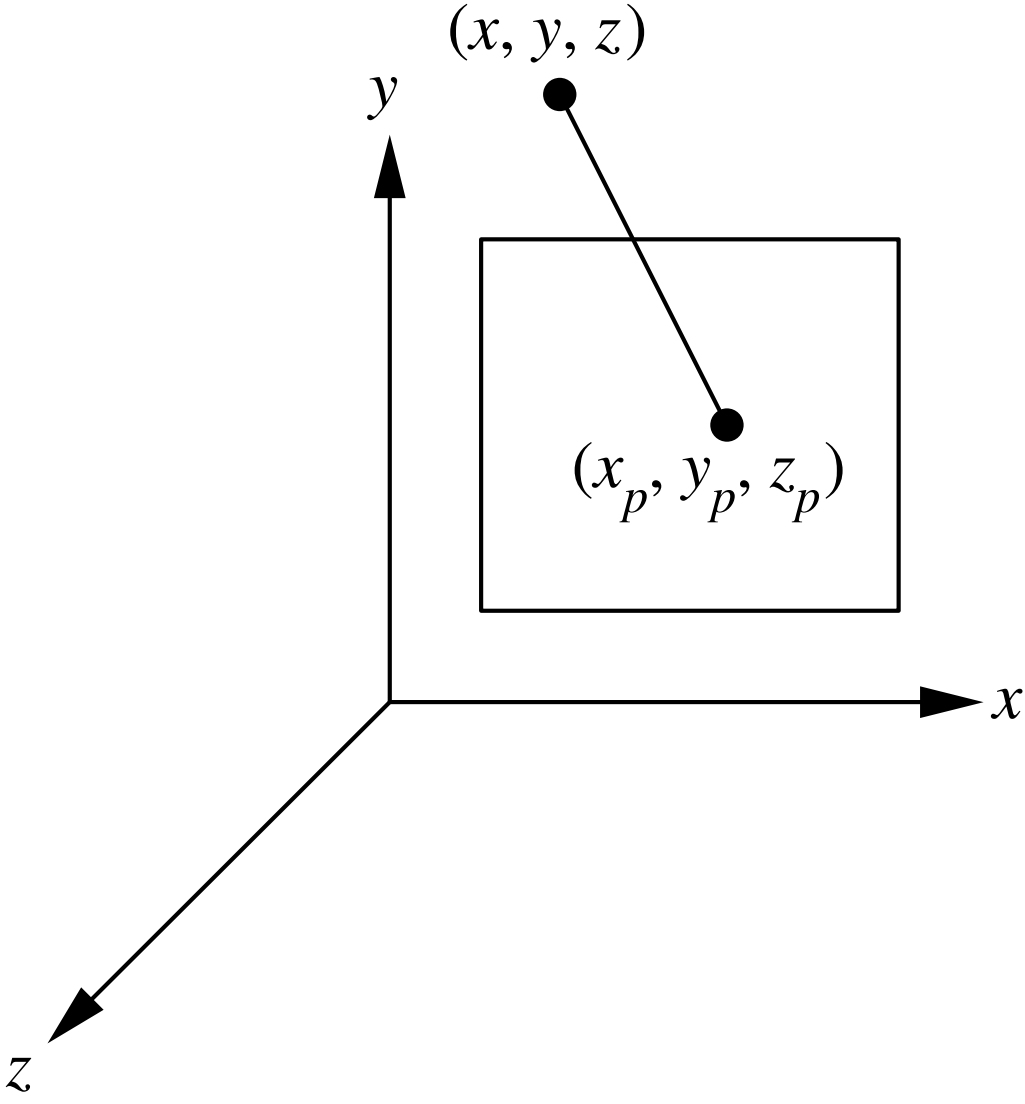
(x, y, z)
y
(x_p, y_p, z_p)
x
z