CS 361, Lecture 21

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Outline

- Red Black Trees (Chapter 13)

Red-Black Properties

A BST is a red-black tree if it satisfies the RB-Properties

1. Every node is either red or black
2. The root is black
3. Every leaf (NIL) is black
4. If a node is red, then both its children are black
5. For each node, all paths from the node to descendant leaves contain the same number of black nodes

HW Questions

- Are there any questions on the current HW?
**Example RB-Tree**

![Example RB-Tree](image)

**Black Height**

- **Black-height** of a node $x$, $bh(x)$ is the number of black nodes on any path from, but not including $x$ down to a leaf node.
- Note that the black-height of a node is well-defined since all paths have the same number of black nodes.
- The black-height of an RB-Tree is just the black-height of the root.

**Key Lemma**

- **Lemma:** A RB-Tree with $n$ internal nodes has height at most $2 \log(n + 1)$
- **Proof Sketch:**
  1. The subtree rooted at the node $x$ contains at least $2^{bh(x)} - 1$ internal nodes.
  2. For the root $r$, $bh(r) \geq h/2$, thus $n \geq 2^{h/2} - 1$. Taking logs of both sides, we get that $h \leq 2 \log(n + 1)$.

**Proof**

1) The subtree rooted at the node $x$ contains at least $2^{bh(x)} - 1$ internal nodes. Show by induction on the height of $x$.

- **BC:** If the height of $x$ is 0, then $x$ is a leaf, and subtree rooted at $x$ does indeed contain $2^0 - 1 = 0$ internal nodes.
- **IH:** For all nodes $y$ of height less than $x$, the subtree rooted at $y$ contains at least $2^{bh(y)} - 1$ internal nodes.
- **IS:** Consider a node $x$ which is an internal node with two children (all internal nodes have two children). Each child has black-height of either $bh(x)$ or $bh(x) - 1$ (the former if it is red, the latter if it is black). Since the height of these children is less than $x$, we can apply the inductive hypothesis to conclude that each child has at least $2^{bh(x) - 1} - 1$ internal nodes. This implies that the subtree rooted at $x$ has at least $(2^{bh(x) - 1}) + (2^{bh(x) - 1} - 1) + 1 = 2^{bh(x)} - 1$ internal nodes. This proves the claim.
• How do we ensure that the Red-Black Properties are maintained?
• I.e. when we insert a new node, what do we color it? How do we re-arrange the new tree so that the Red-Black Property holds?
• How about for deletions?

**Left-Rotate**

- Left-Rotate(x) takes a node x and "rotates" x with its right child
- Right-Rotate is the symmetric operation
- Both Left-Rotate and Right-Rotate preserve the BST Property
- We’ll use Left-Rotate and Right-Rotate in the RB-Insert procedure
Binary Search Tree Property

- Let $x$ be a node in a binary search tree. If $y$ is a node in the left subtree of $x$, then $\text{key}(y) \leq \text{key}(x)$. If $y$ is a node in the right subtree of $x$ then $\text{key}(y) \geq \text{key}(x)$.

In-Class Exercise

Show that Left-Rotate($x$) maintains the BST Property. In other words, show that if the BST Property was true for the tree before the Left-Rotate($x$) operation, then it’s true for the tree after the operation.

- Show that after rotation, the BST property holds for the entire subtree rooted at $x$.
- Show that after rotation, the BST property holds for the subtree rooted at $y$.
- Now argue that after rotation, the BST property holds for the entire tree.

RB-Insert($T, z$)

1. Set left($z$) and right($z$) to be NIL.
2. Let $y$ be the last node processed during a search for $z$ in $T$.
3. Insert $z$ as the appropriate child of $y$ (left child if $\text{key}(z) \leq \text{key}(y)$, right child otherwise).
4. Color $z$ red.
5. Call the procedure RB-Insert-Fixup.

RB-Insert-Fixup($T, z$)

```plaintext
RB-Insert-Fixup(T,z){
    while (color(p(z)) is red){
        case 1: z’s uncle, $y$, is red{
            do case 1
        }
        case 2: z’s uncle, $y$, is black and z is a right child{
            do case 2
        }
        case 3: z’s uncle, $y$, is black and z is a left child{
            do case 3
        }
    }
    color(root(T)) = black;
}
```
Case 1

Loop Invariant

At the start of each iteration of the loop:

- Node $z$ is red
- If parent($z$) is the root, then parent($z$) is black
- If there is a violation of the red-black properties, there is at most one violation, and it is either property 2 or 4. If there is a violation of property 2, it occurs because $z$ is the root and is red. If there is a violation of property 4, it occurs because both $z$ and parent($z$) are red.

Case 2 and 3

Pseudocode

- Detailed Pseudocode for RB-Insert and RB-Insert-Fixup is in the book, Chapter 13.3
- A detailed proof of correctness for RB-Insert-Fixup is in the same Chapter
- Code for RB-Deletion is also in Chapter 13
Other Balanced BSTs

- We'll now briefly discuss some other balanced BSTs
- They all implement Insert, Delete, Lookup, Successor, Predecessor, Maximum and Minimum efficiently

AVL Trees

- Claim: An AVL tree with \(n\) nodes has height \(O(\log n)\)
- Q: For an AVL tree of height \(h\), how many nodes must it have in it?
- A: We can write a recurrence relation. Let \(T(h)\) be the minimum number of nodes in a tree of height \(h\)
  - Then \(T(h) = T(h-1) + T(h-2) + 1\), \(T(2) = T(1) \geq 1\)
  - This is similar to the recurrence relation for Fibonacci numbers! Solution:
    \[
    T(h) = \frac{1}{\sqrt{5}} \left( \frac{1 + \sqrt{5}}{2} \right)^h - 2
    \]

An AVL tree is height-balanced: For each node \(x\), the heights of the left and right subtrees of \(x\) differ by at most 1
- Each node has an additional height field \(h(x)\)
- Claim: An AVL tree with \(n\) nodes has height \(O(\log n)\)

So we have the equation \(n > T(h)\). Let \(\phi = \frac{1+\sqrt{5}}{2}\). Then:

\[
\begin{align*}
  n &\geq \frac{1}{\sqrt{5}} \phi^h - 2 \\
  \log n &\geq \log \left( \frac{1}{\sqrt{5}} \right) + h \log \phi - 1 \\
  \log n - \log \left( \frac{1}{\sqrt{5}} \right) + 1 &\geq h \log \phi \\
  C \cdot \log n &\geq h
\end{align*}
\]

Where the final inequality holds for appropriate constant \(C\), and for \(n\) large enough. The final inequality implies that \(h = O(\log n)\)
AVL Tree Insertion

- After insert into an AVL tree, the tree may no longer be height-balanced
- Need to “fix-up” the subtrees so that they become height-balanced again
- Can do this using rotations (similar to case for RB-Trees)
- Similar story for deletions

B-Trees

- B-Trees are balanced search trees designed to work well on disks
- B-Trees are not binary trees: each node can have many children
- Each node of a B-Tree contains several keys, not just one
- When doing searches, we decide which child link to follow by finding the correct interval of our search key in the key set of the current node.

Disk Accesses

- Consider any search tree
- The number of disk accesses per search will dominate the run time
- Unless the entire tree is in memory, there will usually be a disk access every time an arbitrary node is examined
- The number of disk accesses for most operations on a B-tree is proportional to the height of the B-tree
- I.e. The info on each node of a B-tree can be stored in main memory

B-Tree Properties

The following is true for every node $x$

- $x$ stores keys, $key_1(x), \ldots, key_l(x)$ in sorted order (nondecreasing)
- $x$ contains pointers, $c_1(x), \ldots, c_{l+1}(x)$ to its children
- Let $k_i$ be any key stored in the subtree rooted at the $i$-th child of $x$, then $k_1 \leq key_1(x) \leq k_2 \leq key_2(x) \cdots \leq key_l(x) \leq k_{l+1}$
B-Tree Properties

- All leaves have the same depth
- Lower and upper bounds on the number of keys a node can contain. Given as a function of a fixed integer $t$
  - Every node other than the root must have $\geq (t - 1)$ keys, and $t$ children. If the tree is non-empty, the root must have at least one key (and 2 children)
  - Every node can contain at most $2t-1$ keys, so any internal node can have at most $2t$ children

Note

- The above properties imply that the height of a B-tree is no more than $\log_t \frac{n+1}{2}$, for $t \geq 2$, where $n$ is the number of keys.
- If we make $t$, larger, we can save a larger (constant) fraction over RB-trees in the number of nodes examined
- A (2-3-4)-tree is just a B-tree with $t = 2$

In-Class Exercise

We will now show that for any B-Tree with height $h$ and $n$ keys, $h \leq \log_t \frac{n+1}{2}$, where $t \geq 2$.

Consider a B-Tree of height $h > 1$

- Q1: What is the minimum number of nodes at depth 1, 2, and 3
- Q2: What is the minimum number of nodes at depth $i$?
- Q3: Now give a lowerbound for the total number of keys (e.g. $n \geq ???$)
- Q4: Show how to solve for $h$ in this inequality to get an upperbound on $h$

Splay Trees

- A Splay Tree is a kind of BST where the standard operations run in $O(\log n)$ amortized time
- This means that over $l$ operations (e.g. Insert, Lookup, Delete, etc), where $l$ is sufficiently large, the total cost is $O(l \cdot \log n)$
- In other words, the average cost per operation is $O(\log n)$
- However a single operation could still take $O(n)$ time
- In practice, they are very fast
Skip Lists

- Technically, not a BST, but they implement all of the same operations
- Very elegant randomized data structure, simple to code but analysis is subtle
- They guarantee that, with high probability, all the major operations take $O(\log n)$ time
- We’ll discuss them more next class

Which Data Structure to use?

- Splay trees work very well in practice, the “hidden constants” are small
- Unfortunately, they can not guarantee that every operation takes $O(\log n)$
- When this guarantee is required, B-Trees are best when the entire tree will not be stored in memory
- If the entire tree will be stored in memory, RB-Trees, AVL-Trees, and Skip Lists are good

High Level Analysis

Comparison of various BSTs

- RB-Trees: + guarantee $O(\log n)$ time for each operation, easy to augment, – high constants
- AVL-Trees: + guarantee $O(\log n)$ time for each operation, – high constants
- B-Trees: + works well for trees that won’t fit in memory, – inserts and deletes are more complicated
- Splay Tress: + small constants, – amortized guarantees only
- Skip Lists: + easy to implement, – runtime guarantees are probabilistic only