1 Multiplicative Weights (MW)

Note: These lecture notes are closely based on lecture notes by Aaron Roth [1] from the class CIS 320.

1.1 MultiplicativeWeights

The Problem. Imagine that we have N experts and we are operating in the following regime

- In rounds $1, \ldots, T$, the algorithm chooses some expert i^t
- In round t, each expert i experiences a loss $\ell_i^t \in [0, 1]$. The algorithm experiences the loss of the expert it chooses $\ell_A^t = \ell_{i^t}^t$

In the above, the total loss of expert *i* is $L_i^T = \sum_{t=1}^T \ell_i^t$. The total loss of the algorithm is $L_A^T = \sum_{t=1}^T \ell_A^t$. The goal of the algorithm is to obtain loss not much worse than the best expert: $\min_i L_i^T$.

The Algorithm. The following algorithm solves the above problem. It takes as a parameter the value η .

procedure MULTIPLICATIVEWEIGHTS Set weights $w_i^1 \leftarrow 1$ for all experts ifor t = 1 to T do $W^t \leftarrow \sum_{i=1}^N w_i^t$ Choose expert i with probability w_i^t/W^t For each $i, w_i^{t+1} \leftarrow w_i^t(1 - \eta \ell_i^t)$ end for end procedure

Analysis. The following theorem shows MultiplicativeWeights does quite well.

Theorem 1. Let L_{MW}^T be the loss of MultiplicativeWeights, and k be any expert. Then:

$$\frac{1}{T}E(L_{MW}^T) \le \frac{1}{T}L_k^T + \eta + \frac{\ln N}{\eta T}$$

In particular, setting $\eta = \sqrt{\frac{\ln N}{T}}$, we get

$$\frac{1}{T}E(L_{MW}^T) \le \frac{1}{T}L_k^T + 2\sqrt{\frac{\ln N}{T}}$$

Proof: Let F^t be the expected loss of MultiplicativeWeights in round t. By linearity of expectation, we know $E(L_{MW}^T) = \sum_{t=1}^{T} F^t$. We also know that

$$F^t = \frac{\sum_{i=1}^N w_i^t \ell_i^t}{W^t}$$

So what is W^t ? We know that $W^1 = N$ and by the algorithm:

$$W^{t+1} = W^t - \sum_{i=1}^N \eta w_i^t \ell_i^t = W^t (1 - \eta F^t).$$

Solving this recurrence, we get

$$W^{T+1} = N \prod_{t=1}^{T} (1 - \eta F^t).$$

Taking the log, and using the fact that $\ln(1-x) \leq -x$, we get:

$$\ln W^{T+1} = \ln N + \sum_{t=1}^{T} \ln(1 - \eta F^t)$$
$$\leq \ln N - \eta \sum_{t=1}^{T} F^t$$
$$= \ln N - \eta E(L_{MW}^T)$$

Now using the fact that $W^{T+1} \ge w_k^{T+1}$, and the inequality $\ln(1-x) \ge -x - x^2$, for 0 < x < 1/2, we get for every k that

$$\ln W^{T+1} \ge \ln w_k^{T+1}$$
$$= \sum_{t=1}^T \ln(1 - \eta \ell_k^t)$$
$$\ge -\sum_{t=1}^T \eta \ell_k^t - \sum_{t=1}^T (\eta \ell_k^t)^2$$
$$\ge -\eta L_k^t - \eta^2 T$$

Combining these two bounds, we get:

$$-\eta L_k^t - \eta^2 T \le \ln N - \eta E(L_{MW}^T)$$

Isolating $E(L_{MW}^T)$ we get:

$$E(L_{MW}^T) \le -L_k^t - \eta T + (\ln N)/\eta$$

Dividing by T obtains the theorem statement.

1.2 MWVectorBounded

The Algorithm. The following algorithm is competitive with any linear combination of experts where the linear scalars are all non-negative and sum to 1. It requires that losses are all in the range [0, 1].

```
procedure MWVECTORBOUNDED
Set weights w_i^1 \leftarrow 1 for all experts i
for t = 1 to T do
W^t \leftarrow \sum_{i=1}^N w_i^t
Play vector w^t, where w^t[i] = w_i^t/W_t for i \in [1, N]
For each i, w_i^{t+1} \leftarrow w_i^t(1 - \eta \ell_i^t)
end for
end procedure
```

The Analysis. Recall that $\Delta(N)$ is the set of all length N vectors having all entries non-negative and summing to 1. then we have the following theorem.

Theorem 2. Setting $\eta = \sqrt{\frac{\ln N}{T}}$, for any sequence of losses $\ell^t \in [0, 1]^N$, MWVectorBounded gets: $\frac{1}{T} \sum_{t=1}^T \langle w^t, \ell^t \rangle \leq \min_{w^* \in \Delta(N)} \frac{1}{T} \sum_{t=1}^T \langle w^*, \ell^t \rangle + 2\sqrt{\frac{\ln N}{T}}$

Proof: The left hand side is exactly the expected loss of MultiplicativeWeights. Similarly, the "loss of expert *i*" corresponds to $\sum_{t=1}^{T} \langle e_i, \ell^t \rangle$, where e_i is the standard basis vector with a 1 in position *i* and 0's elsewhere. Finally, observe that for every sequence of possible losses:

$$\min_{w^* \in \Delta(N)} \sum_{t=1}^T \langle w^*, \ell^t \rangle = \sum_{t=1}^T \langle e_{i^*}, \ell^t \rangle$$

where $i^* = \arg \min_{i \in [1,N]} \sum_{t=1}^T \ell_i^T$. So minimizing regret to the best basis vector e_{i*} (i.e. the best expert) implies minimizing regret to the best vector $w^* \in \Delta(N)$. Thus, the result follows by Theorem 1.

1.3 Arbitrary Losses and Vector Sums

Let $B_N(R_1)$ be the set of *n* dimensional vectors with nonnegative entries that sum up to at most R_1 . Below are changes we make to MWVector in order to compete with vectors in $B_N(R_1)$ and handle losses in the range $[-R_2/2, R_2/2]^N$.

```
procedure MWVECTOR (R_1, R_2)

Add a N + 1 expert, with \ell_{N+1}^t = 0 for all t.

Set u_i^1 \leftarrow 1 for all experts i

for t = 1 to T do

U^t \leftarrow \sum_{i=1} u_i^t

Play the vector w^t, where w^t[i] = R_1 u_i^t / U^t for all i

For each i, u_i^{t+1} \leftarrow u_i^t (1 - \eta(\ell_i + R_2/2)/R_2))

end for

end procedure
```

The algorithm makes the following changes compared to MWVectorBounded

- Weights: A N + 1 expert is added that always has loss of 0. The algorithm uses "internal" weights u_i and outputs "external" weights w_i that are now scaled by R_1 .
- Losses: We first add $R_2/2$ to every loss value, and then divide the new loss value by R_2 . This gives normalized loss values all in [0, 1].

Theorem 3. Setting $\eta = \sqrt{\frac{\ln N}{T}}$, for losses $\ell^t \in [-R_2/2, R_2/2]^N$, MWVector obtains:

$$\frac{1}{T}\sum_{t=1}^{T} \langle w^t, \ell^t \rangle \le \min_{w^* \in B_N(R_1)} \frac{1}{T} \sum_{t=1}^{T} \langle w^*, \ell^t \rangle + 2R_1 R_2 \sqrt{\frac{\ln N}{T}}$$

Proof: First note that the N + 1 expert allows for the normalized, "internal" weight values, u_i^t/U^t , to sum to anything in the range [0, 1]. When we scale these values by R_1 , we thus obtain any vector with positive entries that sum to anything less than R_1 . Second note that adding $R_2/2$ to each of the losses does not change the "regret" - i.e. the value $\langle w^2, \ell^t \rangle - \langle w^*, \ell^t \rangle$.

Finally, note that if we divide the coordinates of w_t by R_1 and the coordinates of ℓ_t by R_2 , we get, by Theorem 2, that:

$$\frac{1}{T}\sum_{t=1}^{T}\left\langle\frac{w^t}{R_1},\frac{\ell^t}{R_2}\right\rangle \le \min_{w^*\in B_N(R_1)}\frac{1}{T}\sum_{t=1}^{T}\left\langle\frac{w^*}{R_1},\frac{\ell^t}{R_2}\right\rangle + 2\sqrt{\frac{\ln N}{T}}.$$

Multiplying the above inequality by R_1R_2 gives the promised inequality.

2 Winnow

2.1 Problem

Assume we are given feature vectors, a_1, \ldots, a_m , each having a classification of either -1 or +1. We want to find a hyperplane that correctly separates the points. For simplicity, we can define a_j to be $s_j a_j$, where $s_j \in \{-1, +1\}$ is the classification of example j.

Then, we want to find vector x, such that for each attribute vector $i, x \cdot a_i \ge 0$. Without loss of generality, we can assume that x is in $\Delta(n)$ where n is length of each attribute vector.¹

Example. We are given three feature vectors: (2, -1), class -1; (-4, 1), class 1, (-10, 1), classs -1. Multiplying each vector by its class gives: (-2, 1), (-4, 1), (10, -1). Then, we see that x = (1/10, 9/10) is one vector that correctly classifies all of these.

2.2 Algorithm.

Let N be the number of attributes in each feature vector, i.e. the length of each feature vector. Let M be the maximum value of any entry in any feature vector.

```
procedure WINNOW
```

Run MWVector $(R_1 = 1, R_2 = 2M)$ with the following settings: **Experts:** Associate an expert with each of the N attributes. **Losses:** In round t, find some example a_j , where $\langle w^t, a_j \rangle < 0$. Then set $\ell_i^t \leftarrow -a_j[i]$. When $\langle w^t, a_j \rangle \ge 0$ for all a_j , terminate. end procedure

2.3 Analysis

Suppose there is a vector $v^* \in B_N(1)$ such that for all $j, \langle v^*, a_j \rangle \geq \epsilon$, for some fixed $\epsilon > 0$. Then, we have the following result.

Theorem 4. Winnow terminates in $T \leq \left(\frac{4M\sqrt{\ln N}}{\epsilon}\right)^{2/3}$ rounds.

 $^{^{1}}$ Why? We can simulate negative weights by adding in attributes that are the negative of all the old attributes; this only doubles the number of attributes.

Proof: Let T be the round in which Winnow terminates. Then, for all t < T, $\langle w^t, \ell^t \rangle > 0$. Thus, we have

$$0 < \sum_{t=1}^{T} \langle w^{t}, \ell^{t} \rangle$$

$$\leq \sum_{t=1}^{T} \langle w^{*}, \ell^{t} \rangle + 4M \sqrt{\frac{\ln N}{T}}$$

$$\leq -T\epsilon + 4M \sqrt{\frac{\ln N}{T}}$$

In the above, the second step holds by Theorem 3. The third step holds by noting that $\sum_{t=1}^{T} \langle w^*, \ell^t \rangle \leq \sum_{t=1}^{T} \langle v^*, \ell^t \rangle \leq \epsilon$. Isolating T in the above inequality gives:

$$T \le \left(\frac{4M\sqrt{\ln N}}{\epsilon}\right)^{2/3}$$

3 Minimax Theorem

3.1 Game Theory

Two-players, *Min* and *Max*, are playing a game characterized by a *m* by *n* matrix *C*. Player Min chooses an action from the set $A_1 = \{1, \ldots, m\}$, and player Max chooses an action from the set $A_2 = \{1, \ldots, n\}$. The cost of the game is given by the function $C: A_1 \times A_2 \to \mathbb{R}^2$.

A mixed strategy for Min is a probability distribution over $A_1: p \in \Delta(m)$; a mixed strategy for Max is a probability distribution over $A_2: q \in \Delta(n)$. Then the *expected cost* of the game is

$$C(p,q) = \sum_{i=1}^{m} \sum_{j=1}^{n} C[i,j]p_i q_j = q^T C p.$$

One of the players may play a *pure* strategy - i.e. does not randomize. For example, Max might always play strategy $y \in [n]$. Then we write:

$$C(p, y) = \sum_{i=1}^{m} C[i, y]p_i = (e_y)^T Cp.$$

Example. A example (zero-sum) game is given by the following 3 by 3 payoff matrix C.

	Rock	Paper	Scissors
Rock	0	-1	1
Paper	-1	0	1
Scissors	1	-1	0

 $^{^{2}}$ This type of game where the costs of both players are given by a single matrix is called zero-sum

MaxMin and MinMax. Normally, games are played simultaneously, but what if Min has to announce her (mixed) strategy to Max first? Or vice versa? We can calculate the cost of the game in each case as follows:

$$\max\min(C) = \max_{q \in \Delta(n)} \min_{x \in [m]} \sum_{j=1}^{n} q_i C[x, i]$$
$$\min\max(C) = \min_{p \in \Delta(m)} \max_{y \in [n]} \sum_{i=1}^{m} p_i C[i, y]$$

Note that the player who plays second always just chooses a single action - their *best response* - since there's no need to randomize if you already know your opponents probability distribution.

3.2 Minimax Theorem

It turns out that it doesn't matter which player goes first. In particular, we will show that $\min \max(C) = \max \min(C)$ for all matrices C. We will eventually show this using our Multiplicative Weights algorithm, but first a definition.

Vectors $p \in \Delta(m)$ and $q \in \Delta(n)$ form an ϵ -approximate minimax equilibrium for a game C iff:

$$\max_{y\in[n]}C(p,y)-\epsilon\leq C(p,q)\leq \min_{x\in[m]}C(x,q)+\epsilon$$

The following algorithm will help us obtain such an ϵ -approximate equilibrium over an m by n matrix C, where all entries in C are normalized to be in the range [0, 1]

```
procedure COMPUTEEQ (C, \epsilon)

T \leftarrow \frac{4\log m}{\epsilon^2}

Initialize a copy of MWVectorBounded to run over w^t \in \Delta(m)

for t = 1 to T do

y^t \leftarrow \arg \max_{y \in [n]} C(w^t, y)

\ell_i^t \leftarrow C[i, y_t] for all i \in [m]

Pass \ell^t to the MWVectorBounded algorithm

end for

Return: (\bar{x}, \bar{y}) \leftarrow \left(\frac{1}{T} \sum_{t=1}^T w^t, \frac{1}{T} \sum_{t=1}^T e_{y^t}\right)

end procedure
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Theorem 5. For any $\epsilon > 0$ and any game C, ComputeEQ returns vectors (\bar{x}, \bar{y}) that are an ϵ -approximate minimax equilibrium.

Proof: First, observe that for any $x \in [m]$,

$$\frac{1}{T}\sum_{t=1}^{T}C(x,y^{t}) = C\left(x,\frac{1}{T}\sum_{t=1}^{T}e_{y^{t}}\right)$$
$$= C(x,\bar{y})$$

Similarly, for any $y \in [n]$, $\frac{1}{T} \sum_{t=1}^{T} C(w^t, y) = C(\bar{x}, y)$. These are both true since linearity of the C function allows to push sums and scalars inside it.

Let $x^* = \arg \min_x C(x, \bar{y})$ and $y^* = \arg \max_y C(\bar{x}, y)$. Then, MWVectorBounded ensures, by Theorem 2:

$$\frac{1}{T} \sum_{t=1}^{T} C(w^t, y^t) \le \frac{1}{T} \sum_{t=1}^{T} C(x^*, y^t) + \sqrt{\frac{4\log m}{T}} = C(x^*, \bar{y}) + \sqrt{\frac{4\log m}{T}}$$

Also, by choice of y^t in algorithm ComputeEQ:

$$\frac{1}{T} \sum_{t=1}^{T} C(w^t, y^t) \ge \frac{1}{T} \sum_{t=1}^{T} C(w^t, y^*)$$
$$= C(\bar{x}, y^*)$$

Putting these two inequalities together, we get that:

$$C(\bar{x}, y^*) \le C(x^*, \bar{y}) + \sqrt{\frac{4\log m}{T}}$$

Adding and subtracting $C(\bar{x}, \bar{y})$ and rearranging, we get:

$$(C(\bar{x}, \bar{y}) - C(x^*, \bar{y})) + (C(\bar{x}, y^*) - C(\bar{x}, \bar{y})) \le \sqrt{\frac{4\log m}{T}}$$

By definition of x^* and y^* , both terms on the LHS are non-negative. Hence, both:

$$C(\bar{x},\bar{y}) - C(x^*,\bar{y}) \le \sqrt{\frac{4\log m}{T}} \qquad \qquad C(\bar{x},y^*) - C(\bar{x},\bar{y}) \le \sqrt{\frac{4\log m}{T}}$$

This implies that (\bar{x}, \bar{y}) forms a $\sqrt{\frac{4 \log m}{T}}$ -approximate minimax equilibrium. By our choice of $T, \sqrt{\frac{4 \log m}{T}} \leq \epsilon.$

Now, Von Neumann's minimax theorem follows as a corollary.

Theorem 6. (Von Neumann Minimax) For any zero-sum game C,

$$\min\max(C) = \max\min(C)$$

Proof: By Theorem 5, for any game C and $\epsilon > 0$, we can find \bar{x}, \bar{y} such that:

$$\min\max(C) - \epsilon \le \max_{y \in [n]} C(\bar{x}, y) - \epsilon \le C(\bar{x}, \bar{y}) \le \min_{x \in [m]} C(x, \bar{y}) + \epsilon \le \max\min(C) + \epsilon$$

Thus, $\min \max(C) \leq \max \min(C) + 2\epsilon$ for all $\epsilon > 0$, so $\min \max(C) \leq \max \min(C)$. Since player Min can only do worse when she has the last turn, we also know that $\min \max(C) \geq \max \min(C)$. Thus, the two quantities are equal!

4 Boosting

Define a *labelled datapoint* to be a pair $(x, y) \in X \times Y$, where X is some space of features and Y is some space of labels. Frequently, $X = \mathbb{R}^d$ and $Y = \{0, 1\}$. A *data set* is a collection of labelled datapoints.

Our goal is to find a function $f: X \to Y$ for predicting labels from features with high accuracy. In particular, given a predictor $f: X \to Y$, the accuracy of f on a data set D of n items is:

$$acc(f, D) = \frac{1}{n} \sum_{i=1}^{n} I(f(x_i) = y_i)$$

We can also define weighted prediction accuracy for any weighting $w \in \Delta(n)$ of the *n* points:

$$acc(f, D, w) = \frac{1}{n} \sum_{i=1}^{n} w_i I(f(x_i) = y_i)$$

In the above I(p) is an indicator function which is 1 if the predicate p is true and 0 otherwise

Hypothesis, Learners, and Weak and Strong Learners A hypothesis class H is a collection of hypothesis $h: X \times Y$. A weighted learning algorithm A with range H is a mapping from datasets and weight vectors to hypothesis in H.

A is a weak learning algorithm for D if for every distribution $w \in \Delta(n), A(D, w) = h$ such that:

$$acc(h, D, w) \ge .51$$

A is a strong learning algorithm for D if A(D) = h such that:

$$acc(h, D) = 1$$

4.1 Weak Learner to Strong Learner

Remarkably, we can use a weak learning algorithm for a dataset D to obtain a strong learning algorithm.

Theorem 7. For any dataset D, if there exists a polytime weak learning algorithm for D, then there exists a polytime strong learning algorithm for D.

Proof: Our approach will use game theory. Let H be the hypothesis class used by the weak learning algorithm A. Define a zero-sum game as follows:

- The action space for the Min player ("DATA") is the set of data points: $A_1 = D$.
- The action space for the Max player ("LEARNER") is the $A_2 = H$
- The cost function is defined as: $C((x_i, y_i), h) = I(h(x_i) = y_i))$

Since A is a weak learner for D, we can compute the min max value of the game. In particular, this is how well the player LEARNER can do if the player DATA must go first:

$$\min \max(C) = \min_{w \in \Delta(n)} \max_{h \in H} \sum_{i=1}^{n} w_i C((x_i, y_i), h)$$
$$= \min_{w \in \Delta(n)} \max_{h \in H} \sum_{i=1}^{n} w_i I((h(x_i) = y_i))$$
$$= \min_{w \in \Delta(n)} \max_{h \in H} \sum_{i=1}^{n} acc(h, D, w)$$
$$\ge .51$$

The last line holds since the player LEARNER can use the weak learner algorithm A. But, then we also know:

$$\min \max(C) = \max \min(C)$$
$$= \max_{p \in \Delta(|H|)} \min_{i \in [n]} \sum_{h \in H} p_h I(h(x_i) = y_i)$$
$$> .51$$

The first step follows by the minimax theorem (Theorem 6), since we know player LEARNER can do just as well if she goes second. In the second step, the value p chosen in $\Delta(H)$ is the mixed strategy for player LEARNER. The third step follows by our lowerbound on min max above.

Thus, there is some fixed distribution p^* over hypothesis $h \in H$ such that at least .51 of the hypothesis weighted by p correctly label every point (x_i, y_i) . Consider the following "weighted majority vote" classifier:

$$f_{p^*}(x) = \underset{y \in Y}{\operatorname{arg\,max}} \sum_{h \in H} p^* I(h(x) = y)$$

From our minimax calculations above, we know that for any $(x_i, y_i) \in D$, we have:

$$\sum_{h \in H} p_h I(h(x_i) = y_i) = \sum_{h \in H: h(x_i) = y_i} p_h^* \ge .51$$

Thus, by construction, $f_{p^*}(x_i) = y_i$.

4.2 Some Details and Resource Analysis

Note that algorithm ComputeEQ can only compute an ϵ -equilibrium, not an exact one. But that's not a problem so long as we set ϵ small enough so that payoff of the game is still > .5. For example, $\epsilon = .001$ works fine since .51 - .001 > .5 holds.

4.2.1 Algorithm

So what does the final algorithm look like if we "inline" the call to ComputeEQ? A direct version of our algorithm Boost, for dataset D, and weak-learning algorithm A is given below. Recall that the weak-learning algorithm A can, for any weighting w of data set D, always find a hypothesis $h \in H$ that correctly classifies at least a .51 weighted fraction of the items in D. Finally, let n = |D| and m = |H|.

In the following algorithm, the weight vector, w^t , gives the strategy for player DATA, and the (weighted) h^t values give the strategy for the player LEARNER.

procedure BOOST (D, A) $T \leftarrow \frac{4 \log n}{\epsilon^2}$ Initialize a copy of MWVectorBounded to run over $w^t \in \Delta(n)$ **for** t = 1 to T **do** $h^t \leftarrow A(D, w^t)$ $\ell_i^t \leftarrow I(h^t(x_i) = y_i)$ for all $i \in [m]$ Pass ℓ^t to the MWVectorBounded algorithm **end for** $\bar{p} \leftarrow \frac{1}{T} \sum_{t=1}^T e_{h^t}$ Return: $f_{\bar{p}}(x)$, where $f_{\bar{p}}(x) = \arg \max_{y \in Y} \sum_{h \in H} \bar{p}_h I(h(x) = y)$ **end procedure**

4.2.2 Analysis

How long does our algorithm Boost run for? Since ϵ is a constant, on a dataset of size n, it runs for $O(\log n)$ iterations. In each round, it makes a single call to the weak learning algorithm A, which we assume is polynomial. Then it updates the weight distributions over the n data points in D, which takes O(n).

Note that the function $f_{\bar{p}}(x)$ is concisely representable since \bar{p} has support over only the $T = O(\log n)$ hypothesis, h^t , chosen at the start of each iteration.

Finally, note that if the weak learner returns "simple" functions such as linear classifiers or depth-2 decision trees, then the function $f_{\bar{p}}(x)$ will also not be too complex. In particular, it can be described as the average of no more than $O(\log n)$ of these simple functions. This simplicity is a positive indication that $f_{\bar{p}}(x)$ will generalize well, performing well not just on the training data, but also on the test data.

References

 Aaron Roth. Polynomial Weights, 2021. https://www.cis.upenn.edu/~aaroth/courses/ MWlectures.pdf.