

One-dimensional Random Walk

Consider the following Markov process:

$$p_{t+1}(i) = \sum_{j=0}^{N-1} p_{t+1|t}(i | j) p_t(j)$$

where $i, j \in \{0, 1, \dots, N-1\}$ and

$$p_{t+1|t}(i | j) = \begin{cases} (1 - 2\gamma) & \text{if } i = j \\ \gamma & \text{if } i = j \pm 1 \bmod N \\ 0 & \text{otherwise.} \end{cases}$$

One-dimensional Random Walk (contd.)

All of this can be expressed more concisely in matrix notation:

$$\mathbf{x}^{(t+1)} = \mathbf{P}\mathbf{x}^{(t)}$$

where \mathbf{P} is a stochastic matrix:

$$\mathbf{P} = \begin{bmatrix} (1-2\gamma) & \gamma & 0 & \dots & 0 & \gamma \\ \gamma & (1-2\gamma) & \gamma & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \gamma & 0 & 0 & \dots & \gamma & (1-2\gamma) \end{bmatrix}.$$

Because the random walk is shift-invariant, \mathbf{P} is circulant.

Diffusion in the Frequency Domain

It follows that \mathbf{P} is diagonalized by the DFT:

$$\mathbf{P} = \mathbf{W}\Lambda\mathbf{W}^*.$$

The matrix Λ contains the eigenvalues of \mathbf{P} on its diagonal:

$$\Lambda = \begin{bmatrix} \lambda_0 & 0 & 0 & \dots & 0 \\ 0 & \lambda_1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda_{N-1} \end{bmatrix}.$$

where $\lambda_0 \dots \lambda_{N-1}$ are the (unnormalized) DFT of the first column of $\mathbf{P} = [p_{ij}]$:

$$\begin{aligned} \lambda_m &= \sum_{n=0}^{N-1} p_{n0} e^{-j2\pi m \frac{n}{N}} \\ &= (1 - 2\gamma) + \gamma e^{-j2\pi m \frac{1}{N}} + \gamma e^{-j2\pi m \frac{(N-1)}{N}}. \end{aligned}$$

which is real.

Diffusion in the Frequency Domain (contd.)

The update equation for the Markov chain looks like this:

$$\mathbf{x}^{(t+1)} = \mathbf{W}\Lambda\mathbf{W}^*\mathbf{x}^{(t)}.$$

Higher powers of \mathbf{P} are easy to compute:

$$\mathbf{P}^t = \mathbf{W}\Lambda^t\mathbf{W}^*$$

where

$$\Lambda^t = \begin{bmatrix} \lambda_0^t & 0 & 0 & \dots & 0 \\ 0 & \lambda_1^t & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda_{N-1}^t \end{bmatrix}.$$

Finally, given an initial distribution, $\mathbf{x}^{(0)}$, the distribution at time, t , is:

$$\mathbf{x}^{(t)} = \mathbf{W}\Lambda^t\mathbf{W}^*\mathbf{x}^{(0)}.$$

Diffusion Equation

The following expression for P_x^{t+1} in terms of P_x^t , P_{x+1}^t , and P_{x-1}^t is termed the *master equation* for the *diffusion* process:

$$P_x^{t+1} = P_x^t - 2\gamma P_x^t + \gamma P_{x-1}^t + \gamma P_{x+1}^t$$

where $2\gamma P_x^t$ is the probability mass which leaves P_x^t in one step and $\gamma P_{x-1}^t + \gamma P_{x+1}^t$ is the probability mass which enters P_x^t in one step.

Diffusion Equation (contd.)

The above expression for $\Delta t = \Delta x = 1$ can be generalized for arbitrary Δt and Δx by defining $\gamma = D \frac{\Delta t}{(\Delta x)^2}$:

$$P_x^{t+\Delta t} = P_x^t - \underbrace{2DP_x^t \frac{\Delta t}{(\Delta x)^2}}_{\text{out}} + \underbrace{DP_{x-\Delta x}^t \frac{\Delta t}{(\Delta x)^2} + DP_{x+\Delta x}^t \frac{\Delta t}{(\Delta x)^2}}_{\text{in}}$$

where D is termed the *diffusion constant*. Solving for $(P_x^{t+\Delta t} - P_x^t) / \Delta t$ yields:

$$\begin{aligned} & (P_x^{t+\Delta t} - P_x^t) / \Delta t \\ &= (DP_{x+\Delta x}^t - 2DP_x^t + DP_{x-\Delta x}^t) / (\Delta x)^2 \\ &= (DP_{x+\Delta x}^t - DP_x^t + DP_{x-\Delta x}^t - DP_x^t) / (\Delta x)^2 \end{aligned}$$

Diffusion Equation (contd.)

$$\begin{aligned} & (P_x^{t+\Delta t} - P_x^t) / \Delta t \\ &= D (P_{x+\Delta x}^t - P_x^t + P_{x-\Delta x}^t - P_x^t) / (\Delta x)^2 \\ &= D [(P_{x+\Delta x}^t - P_x^t) - (P_x^t - P_{x-\Delta x}^t)] / (\Delta x)^2 \end{aligned}$$

which can be rewritten as follows:

$$\frac{P_x^{t+\Delta t} - P_x^t}{\Delta t} = D \frac{\left[\frac{P_{x+\Delta x}^t - P_x^t}{\Delta x} - \frac{P_x^t - P_{x-\Delta x}^t}{\Delta x} \right]}{\Delta x}.$$

Diffusion Equation (contd.)

Taking the limit as $\Delta x = \Delta t \rightarrow 0$:

$$\lim_{\Delta t \rightarrow 0} \frac{(P_x^{t+\Delta t} - P_x^t)}{\Delta t} =$$
$$\lim_{\Delta x \rightarrow 0} D \frac{\left[\frac{(P_{x+\Delta x}^t - P_x^t)}{\Delta x} - \frac{(P_x^t - P_{x-\Delta x}^t)}{\Delta x} \right]}{\Delta x}$$

yields a *partial differential equation* (PDE):

$$\frac{\partial P}{\partial t} = D \frac{\partial^2 P}{\partial x^2}$$

which is known as the *diffusion equation*.

Finite Difference Approximation of $\frac{\partial P}{\partial x}$

The value of the function, P , at the point, $(x + \Delta x, t)$, can be expressed as a Taylor series expansion about the point, (x, t) , as follows:

$$P_{x+\Delta x}^t = P_x^t + \Delta x \left. \frac{\partial P}{\partial x} \right|_{x,t} + \frac{(\Delta x)^2}{2!} \left. \frac{\partial^2 P}{\partial x^2} \right|_{x,t} + O[(\Delta x)^3].$$

By rearranging the above, we derive the *forward difference* approximation for $\left. \frac{\partial P}{\partial x} \right|_{x,t}$:

$$\frac{P_{x+\Delta x}^t - P_x^t}{\Delta x} = \left. \frac{\partial P}{\partial x} \right|_{x,t} + O[\Delta x].$$

Backward Difference Approximation of $\frac{\partial P}{\partial x}$

The value of the function, P , at the point, $(x - \Delta x, t)$, can be expressed as a Taylor series expansion about the point, (x, t) , as follows:

$$P_{x-\Delta x}^t = P_x^t - \Delta x \frac{\partial P}{\partial x} \Big|_{x,t} + \frac{(-\Delta x)^2}{2!} \frac{\partial^2 P}{\partial x^2} \Big|_{x,t} + O[(\Delta x)^3].$$

By rearranging the above, we derive the *backward difference* approximation for $\frac{\partial P}{\partial x} \Big|_{x,t}$:

$$\frac{P_x^t - P_{x-\Delta x}^t}{\Delta x} = \frac{\partial P}{\partial x} \Big|_{x,t} + O[\Delta x].$$

Centered Difference Approximation of $\frac{\partial P}{\partial x}$

$$P_{x+\Delta x}^t = P_x^t + \Delta x \left. \frac{\partial P}{\partial x} \right|_{x,t} + \frac{(\Delta x)^2}{2!} \left. \frac{\partial^2 P}{\partial x^2} \right|_{x,t} + \frac{(\Delta x)^3}{3!} \left. \frac{\partial^3 P}{\partial x^3} \right|_{x,t} + O[(\Delta x)^4]$$

$$P_{x-\Delta x}^t = P_x^t - \Delta x \left. \frac{\partial P}{\partial x} \right|_{x,t} + \frac{(-\Delta x)^2}{2!} \left. \frac{\partial^2 P}{\partial x^2} \right|_{x,t} + \frac{(-\Delta x)^3}{3!} \left. \frac{\partial^3 P}{\partial x^3} \right|_{x,t} + O[(\Delta x)^4]$$

Subtracting $P_{x-\Delta x}^t$ from $P_{x+\Delta x}^t$ yields:

$$P_{x+\Delta x}^t - P_{x-\Delta x}^t = 2\Delta x \left. \frac{\partial P}{\partial x} \right|_{x,t} + 2 \frac{(-\Delta x)^3}{3!} \left. \frac{\partial^3 P}{\partial x^3} \right|_{x,t} + O[(\Delta x)^4].$$

Centered Difference Approx. of $\frac{\partial P}{\partial x}$ (contd.)

This can be rearranged to yield the *centered difference* approximation for $\frac{\partial P}{\partial x}$:

$$\frac{P_{x+\Delta x}^t - P_{x-\Delta x}^t}{2\Delta x} = \left. \frac{\partial P}{\partial x} \right|_{x,t} + O[(\Delta x)^2].$$

Notice that the centered difference approximation is second order accurate.

Finite Difference Approximation of $\frac{\partial^2 P}{\partial x^2}$

The value of the function, $\partial P / \partial x$, at the point, $(x + \Delta x, t)$, can be expressed as a Taylor series expansion about the point, (x, t) , as follows:

$$\begin{aligned} \left. \frac{\partial P}{\partial x} \right|_{x+\Delta x, t} &= \left. \frac{\partial P}{\partial x} \right|_{x, t} + \\ \Delta x \left. \frac{\partial^2 P}{\partial x^2} \right|_{x, t} &+ \frac{(\Delta x)^2}{2!} \left. \frac{\partial^3 P}{\partial x^3} \right|_{x, t} + O[(\Delta x)^3]. \end{aligned}$$

Given the above we can derive the forward difference approximation for $\frac{\partial^2 P}{\partial x^2} \big|_{x, t}$:

$$\frac{\left. \frac{\partial P}{\partial x} \right|_{x+\Delta x, t} - \left. \frac{\partial P}{\partial x} \right|_{x, t}}{\Delta x} = \left. \frac{\partial^2 P}{\partial x^2} \right|_{x, t} + O[\Delta x].$$

Finite Difference Approx. of $\frac{\partial^2 P}{\partial x^2}$ (contd.)

For reasons of symmetry, we approximate $\frac{\partial P}{\partial x}|_{x+\Delta x, t}$ and $\frac{\partial P}{\partial x}|_{x, t}$ using backward differences:

$$\frac{\left[\frac{P_{x+\Delta x}^t - P_x^t}{\Delta x} - \frac{P_x^t - P_{x-\Delta x}^t}{\Delta x} \right]}{\Delta x} = \frac{\partial^2 P}{\partial x^2} \Big|_{x, t} + O[\Delta x].$$

Combining terms yields the following expression for $\frac{\partial^2 P}{\partial x^2}|_{x, t}$:

$$\frac{P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t}{(\Delta x)^2} = \frac{\partial^2 P}{\partial x^2} \Big|_{x, t} + O[\Delta x].$$

Diffusion Equation (reprise)

Applying the finite difference approximations we've derived to the diffusion equation:

$$\frac{\partial P}{\partial t} = D \frac{\partial^2 P}{\partial x^2}$$

yields

$$\frac{P_x^{t+\Delta t} - P_x^t}{\Delta t} = D \left(\frac{P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t}{(\Delta x)^2} \right)$$

which can be re-arranged to yield:

$$\frac{P_x^{t+\Delta t} - P_x^t}{\Delta t} = D \frac{\left[\frac{P_{x+\Delta x}^t - P_x^t}{\Delta x} - \frac{P_x^t - P_{x-\Delta x}^t}{\Delta x} \right]}{\Delta x}$$

which (we recall) is equivalent to the master equation:

$$P_x^{t+\Delta t} = P_x^t - 2D P_x^t \frac{\Delta t}{(\Delta x)^2} + D P_{x-\Delta x}^t \frac{\Delta t}{(\Delta x)^2} + D P_{x+\Delta x}^t \frac{\Delta t}{(\Delta x)^2}.$$

Wave Equation

The partial differential equation governing wave motion is:

$$\frac{\partial^2 P}{\partial t^2} = c^2 \frac{\partial^2 P}{\partial x^2}.$$

Applying the finite difference approximations for $\frac{\partial^2 P}{\partial t^2}|_{x,t}$ and $\frac{\partial^2 P}{\partial x^2}|_{x,t}$ yields:

$$\frac{P_x^{t+\Delta t} - 2P_x^t + P_x^{t-\Delta t}}{(\Delta t)^2} \approx c^2 \left(\frac{P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t}{(\Delta x)^2} \right).$$

Solving for $P_x^{t+\Delta t}$ gives the following update formula:

$$P_x^{t+\Delta t} = -P_x^{t-\Delta t} + 2 \left[1 - c^2 \left(\frac{\Delta t}{\Delta x} \right)^2 \right] P_x^t + c^2 \left(\frac{\Delta t}{\Delta x} \right)^2 (P_{x+\Delta x}^t + P_{x-\Delta x}^t).$$

First Order in Time

Unfortunately, this formula is second-order in time. To derive a formula which is first-order in time, we recall that

$$\frac{\partial^2 P}{\partial t^2} \Big|_{x,t} = \frac{\frac{\partial P}{\partial t} \Big|_{x,t+\Delta t} - \frac{\partial P}{\partial t} \Big|_{x,t}}{\Delta t} + \mathcal{O}[\Delta t].$$

Replacing $\frac{\partial P}{\partial t} \Big|_{x,t+\Delta t}$ with $\frac{P_x^{t+\Delta t} - P_x^t}{\Delta t}$ and using the resulting expression for $\frac{\partial^2 P}{\partial t^2} \Big|_{x,t}$ and a centered difference approximation for $\frac{\partial^2 P}{\partial x^2} \Big|_{x,t}$ in the wave equation yields:

$$\frac{\frac{P_x^{t+\Delta t} - P_x^t}{\Delta t} - \frac{\partial P}{\partial t} \Big|_{x,t}}{\Delta t} \approx c^2 \left(\frac{P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t}{(\Delta x)^2} \right).$$

Multiplying both sides by Δt :

$$\frac{P_x^{t+\Delta t} - P_x^t}{\Delta t} - \dot{P}_x^t \approx c^2 \frac{\Delta t}{(\Delta x)^2} (P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t).$$

First Order in Time (contd.)

Multiplying both sides by Δt again, and then adding P_x^t and $\Delta t \dot{P}_x^t$ to both sides yields:

$$P_x^{t+\Delta t} \approx P_x^t + \Delta t \dot{P}_x^t + c^2 \left(\frac{\Delta t}{\Delta x} \right)^2 (P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t)$$

which can be rearranged to give an update equation for P which is first-order in time:

$$P_x^{t+\Delta t} = \left[1 - 2c^2 \left(\frac{\Delta t}{\Delta x} \right)^2 \right] P_x^t + \Delta t \dot{P}_x^t + c^2 \left(\frac{\Delta t}{\Delta x} \right)^2 (P_{x+\Delta x}^t + P_{x-\Delta x}^t) .$$

First Order in Time (contd.)

To derive an update equation for \dot{P} which is also first-order in time, we once again begin with

$$\frac{\partial^2 P}{\partial t^2} \Big|_{x,t} = \frac{\frac{\partial P}{\partial t} \Big|_{x,t+\Delta t} - \frac{\partial P}{\partial t} \Big|_{x,t}}{\Delta t} + \mathcal{O}[\Delta t].$$

Using the above and a centered difference approximation for $\frac{\partial^2 P}{\partial x^2} \Big|_{x,t}$ in the wave equation results in:

$$\frac{\frac{\partial P}{\partial t} \Big|_{x,t+\Delta t} - \frac{\partial P}{\partial t} \Big|_{x,t}}{\Delta t} \approx c^2 \left(\frac{P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t}{(\Delta x)^2} \right).$$

Writing \dot{P}_x^t for $\frac{\partial P}{\partial t} \Big|_{x,t}$ yields the following update equation for \dot{P} :

$$\dot{P}_x^{t+\Delta t} = \dot{P}_x^t + c^2 \frac{\Delta t}{(\Delta x)^2} (P_{x+\Delta x}^t - 2P_x^t + P_{x-\Delta x}^t).$$

We observe that the update equations for both P and \dot{P} are first-order in time.